



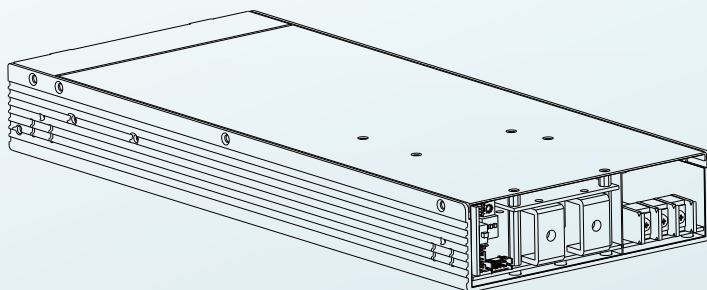
BIC-2200 Series

Installation manual



Bidirectional Power Supply

• High efficiency • Lightweight • Intelligent



The BIC-2200 is a 2.2KW bidirectional power supply with energy recycle function. It is fully digital and 1U height designed. It is designed to control the power transferred from AC grid to DC and DC to AC grid for energy recycle. The implementation of a bidirectional power supply of the BIC-2200 allows battery manufactures to charge the battery from AC grid and recycle the DC energy back into AC grid in one single unit. With built-in functions such as active current sharing, remote ON/OFF control and CANBus model available, the BIC-2200 provides vast design flexibility for battery formation & test equipment, V2G(Vehicle-to-grid) system, charging station, laser system and kinetic recovery system.

Contents

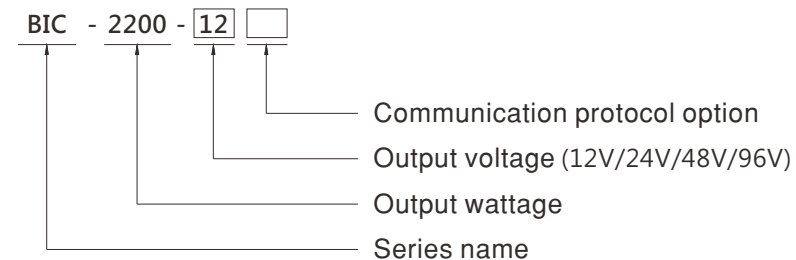
1.Safety Guidelines	1	6.CANBus Protocol	24
2.Introduction	2	6.1 CANBus Specification	24
2.1 Model Encoding	2	6.2 CANBus Addressing	26
2.2 Features	2	6.3 CANBus command list	29
2.3 Specification	3	6.4 Communication	37
2.4 Derating curve	5	Examples	
2.5 Mechanical specification	6	6.5 CANBus value range and tolerance	40
3.Installation & Wiring	7	7.Protections and Trouble Shooting	42
3.1 Precautions	7	7.1 Protections	43
3.2 Installation Procedures	7	7.2 Trouble Shooting	43
3.3 DC Cable Size Selection	8	8.Warranty	44
4.User Interface	9	9.Environmental declaration information	44
4.1 Panel Description	9		
4.2 LED Indicator	10		
4.3 Pin Assignment of CN46	10		
4.4 Pin Assignment of CN47	12		
4.5 Function Description of SW50	12		
4.6 Function Description of DIP Switch	13		
5.Operation	14		
5.1 Description of Bidirectional Operation	14		
5.2 Inrush Current Limiting	19		
5.3 Power Factor Correction (PFC)	19		
5.4 Fan Speed control	19		
5.5 Fault Signal	20		
5.6 ($\overline{\text{DC-OK}}$) Signal	20		
5.7 Remote Control	20		
5.8 Auxiliary Output	21		
5.9 Parallel Operation	21		
5.10 Restore Factory Default Setting	23		

1.Safety Guidelines

- Risk of electrical shock and energy hazard, all failure should be examined by a qualified technician. Please do not remove the case form the bidirectional power supply by yourself.
- Please do not install the supply in places with high moisture, high ambient temperature or under direct sunlight.
- The AC voltage range is 180 – 260Vac (47 – 63Hz), please do not connect the supply to AC gird out of the range.
- Fans and ventilation holes must be kept free from any obstructions. At least 15 cm clearance must be kept when the adjacent device is a heat source.
- Please do not stack any object on the unit.
- The safety protection level of this supply is class I. The "Frame Ground" (≡) of the unit must be well connected to PE (Protective Earth).
- BIC-2200 should be installed in al pollution degree 2 environment.
- Icc=7.5kA ; Icp, mr=200A.

2.Introduction

2.1 Model Encoding



Type	Communication Protocol	Note
Blank	None protocol	In Stock
CAN	CANBus protocol	In Stock

2.2 Features

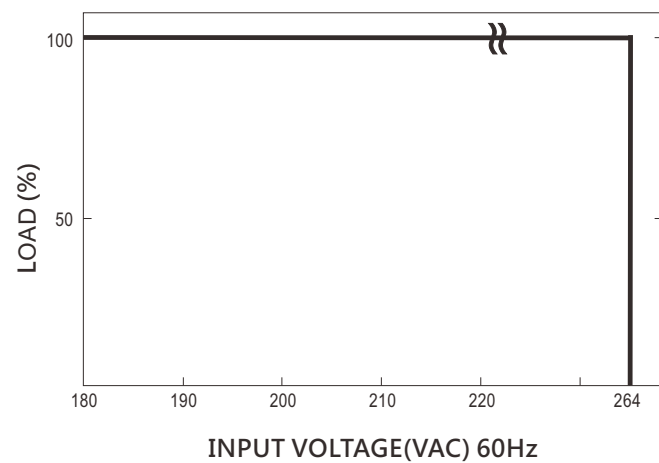
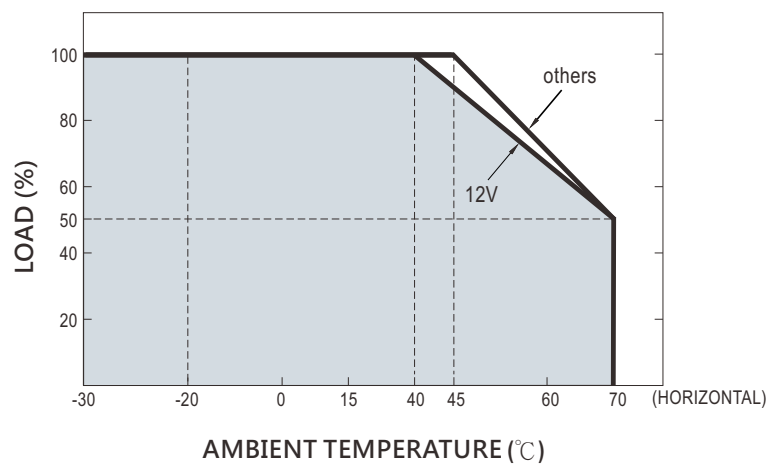
- 1U low profile design
- Full digital design with 93% conversion efficiency for both AC/DC and DC/AC conversion
- Ultrafast switching time between AC/DC and DC/AC of 1ms
- CB/TUV/UL 62368-1 and CB/TUV 62477-1 certified
- Active current sharing up to 19800W (up to 9 unit)
- <3% Low THDi in both conversion mod
- Force charging and discharging mode with CANBus model
- Complete protections: Anti-islanding protection, AC fail protection, DC OVP,OLP, OCP, OTP
- Apply BIC-2200 to a three-phase AC power system
- 5 years warranty

2.3 Specification

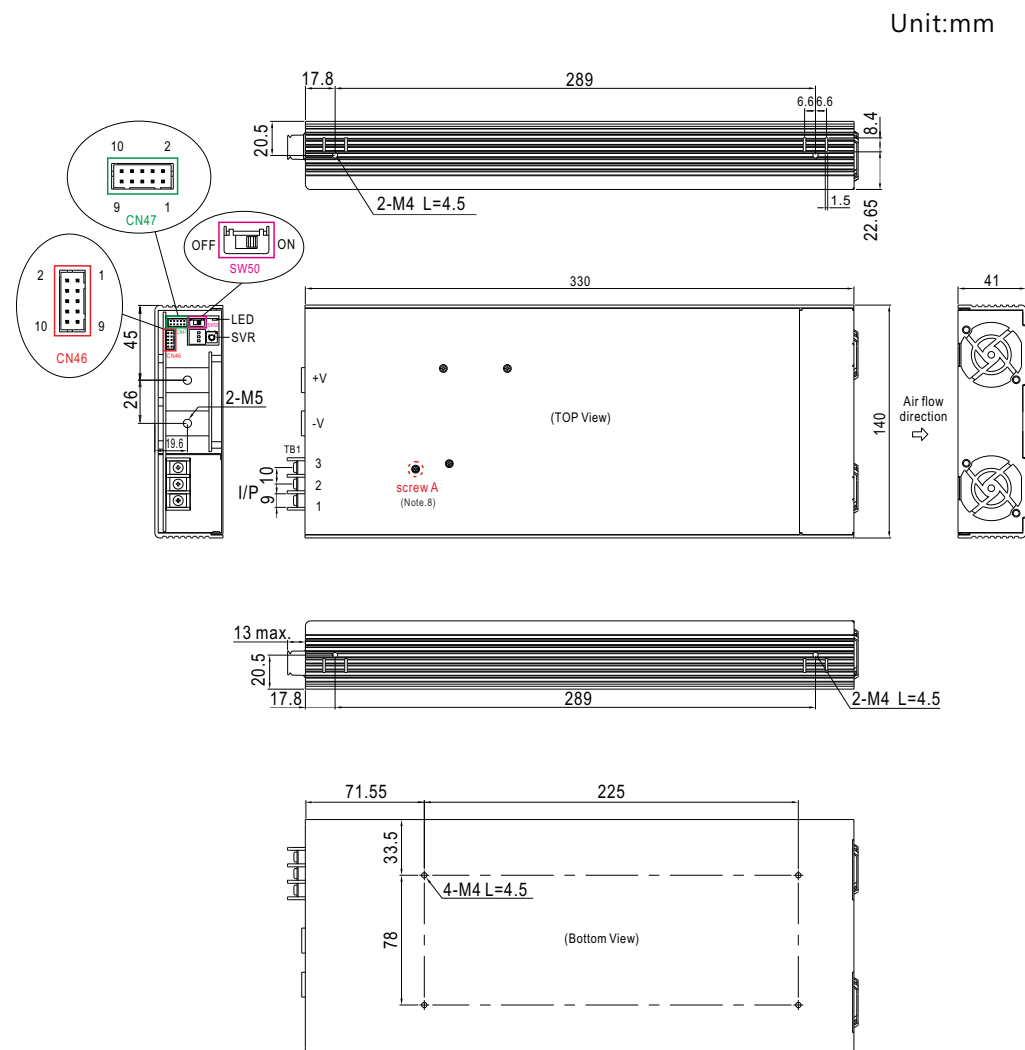
MODEL		BIC-2200-12		BIC-2200-24		BIC-2200-48		BIC-2200-96			
AC to DC Direction	OUTPUT	DC VOLTAGE	12V		24V		48V		96V		
		RATED CURRENT	180A		90A		45A		22.5A		
		RATED POWER	2160W								
		FULL POWER VOLTAGE RANGE	12 ~ 15V		24 ~ 28V		48 ~ 65V		96 ~ 112V		
		RIPPLE & NOISE (max.)	Note.2	160mVp-p		260mVp-p		300mVp-p		480mVp-p	
		VOLTAGE ADJ. RANGE	10 ~ 15V		19 ~ 28V		38 ~ 65V		76 ~ 112V		
		CURRENT ADJ. RANGE	0 ~ 180A		0 ~ 90A		0 ~ 45A		0 ~ 22.5A		
		VOLTAGE TOLERANCE	Note.3	± 1.0%		± 1.0%		± 1.0%		± 1.0%	
		LINE REGULATION	± 0.5%		± 0.5%		± 0.5%		± 0.5%		
	LOAD REGULATION	± 0.5%		± 0.5%		± 0.5%		± 0.5%			
	SETUP, RISE TIME	1800ms, 60ms/230VAC at full load									
	INPUT	AC VOLTAGE RANGE	180 ~ 264VAC								
		FREQUENCY RANGE	47 ~ 63Hz								
		POWER FACTOR (Typ.)	0.98/230VAC at full load								
		EFFICIENCY (Typ.)	Note.5	90%	93%	93%	93%				
		AC CURRENT (Typ.)	11A/230VAC								
INRUSH CURRENT (Typ.)		COLD START 35A/230VAC									
LEAKAGE CURRENT		<2mA/230VAC									
TOTAL HARMONIC DISTORTION		<3% (@load=100%/230VAC)									
DC to AC Direction	INPUT (Note.4)	RATED INPUT POWER	1800W								
		FULL POWER VOLTAGE RANGE	12 ~ 15V		24 ~ 28V		48 ~ 65V		96 ~ 112V		
		DC VOLTAGE RANGE	10 ~ 15V		19 ~ 28V		38 ~ 65V		76 ~ 112V		
		MAX. INPUT CURRENT	150A		75A		37.5A		18.75A		
	OUTPUT	OUTPUT POWER (Typ.) (@240V)	1685W		1720W		1720W		1685W		
		VOLTAGE RANGE	180 ~ 264VAC determined by AC main								
		FREQUENCY RANGE	47 ~ 63Hz determined by AC main								
		AC CURRENT (Typ.)	7.5A/230VAC								
		POWER FACTOR (Typ.)	0.99/230VAC at full load								
		EFFICIENCY (Typ.)	Note.5	90.5%	93%	93%	93%				
		TOTAL HARMONIC DISTORTION	<3% (@load>100%/230VAC)								
		PROTECTION	OVER LOAD	105 ~ 115% rated output power							
AC to DC	Constant current limiting, shut down DC O/P voltage 5 sec. after DC O/P voltage is down low, re-power on to recover										
DC to AC	Not accurable with constant power design										
SHORT CIRCUIT	Shut down O/P current, re-power on to recover										
OVER VOLTAGE	17.6 ~ 20.8V		33.6 ~ 39.2V		72.6 ~ 86V		134 ~ 157V				
OVER TEMPERATURE	Protection type : Shut down O/P voltage, re-power on to recover										
ISLANDING PROTECTION	Shut down O/P voltage, recovers automatically after temperature goes down Shut down AC O/P voltage, re-power on to recover										
FUNCTION	REMOTE ON-OFF CONTROL	By electrical signal or dry contact Short: Power ON Open: Power OFF Please refer to the Function Manual infollowing									
	BIDIRECTION SWITCH TIME(Typ.)	1ms									
	ALARM SIGNAL	Isolated TTL signal output for T-Alarm, DC-OK and Fault Please refer to the Function Manual in following pages									
	AUXILIARY POWER	12V@0.5A tolerance ± 5%, ripple 150mVp-p									
	BATTERY MODE RATED CURRENT(default)	Note.7	AC to DC	160A	80A	40A	20A				
			Can be adjusted by communication								
DC to AC			120A	64A	32A	16A					
Can be adjusted by communication											

MODEL		BIC-2200-12	BIC-2200-24	BIC-2200-48	BIC-2200-96	
ENVIRONMENT	WORKING TEMP.	-30 ~ +70℃ (Refer to "Derating Curve")				
	WORKING HUMIDITY	20 ~ 90% RH non-condensing				
	STORAGE TEMP., HUMIDITY	-40 ~ +85℃, 10 ~ 95% RH non-condensing				
	TEMP. COEFFICIENT	±0.03%/℃ (0 ~ 45℃)				
	VIBRATION	10 ~ 500Hz, 2G 10min./1cycle, 60min. each along X, Y, Z axes				
SAFETY & EMC	SAFETY STANDARDS	UL62368-1, IEC62368-1, CAN/CSA C22.2 No.62368-1,TUV BS EN/EN62368-1, EAC TP TC 004, IEC62477-1, TUV BS EN/EN62477-1 approved				
	WITHSTAND VOLTAGE	Note.8	I/P-O/P:3KVAC I/P-FG:2KVAC O/P-FG:500VAC			
	ISOLATION RESISTANCE	Note.8	I/P-O/P, I/P-FG, O/P-FG:100M Ohms / 500VDC / 25℃ / 70% RH			
	EMC EMISSION	BS EN/EN55032				
		Parameter	Standard		Test Level / Note	
		Conducted	BS EN/EN55032 (CISPR32)		Class A	
		Radiated	BS EN/EN55032 (CISPR32)		Class A	
		Harmonic Current	BS EN/EN61000-3-2		Class A	
		Voltage Flicker	BS EN/EN61000-3-3		-----	
	EMC IMMUNITY	BS EN/EN55035, BS EN/EN61000-6-2				
		Parameter	Standard		Test Level / Note	
		ESD	BS EN/EN61000-4-2		Level 3, 8KV air ; Level 2, 4KV contact	
		Radiated	BS EN/EN61000-4-3		Level 3	
		EFT / Burst	BS EN/EN61000-4-4		Level 3	
		Surge	BS EN/EN61000-6-2		2KV/Line-Line 4KV/Line-Earth	
		Conducted	BS EN/EN61000-4-6		Level 3	
		Magnetic Field	BS EN/EN61000-4-8		Level 4	
		Voltage Dips and Interruptions	BS EN/EN61000-4-11		>95% dip 0.5 periods, 30% dip 25 periods >95% interruptions 250 periods	
OTHERS	MTBF	462.9K hrs min. Telcordia SR-332 (Bellcore) ; 46K hrs min. MIL-HDBK-217F (25℃)				
	DIMENSION	330*140*41mm (L*W*H)				
	PACKING	2.9Kg; 4pcs/12.6Kg/1.25CUFT				
NOTE		1. All parameters NOT specially mentioned are measured at 230VAC input, rated load and 25℃ of ambient temperature. 2. Ripple & noise are measured at 20MHz of bandwidth by using a 12" twisted pair-wire terminated with a 0.1uf & 47uf parallel capacitor. 3. Tolerance : includes set up tolerance, line regulation and load regulation. 4. As a constant power output, the driver will auto derating the current limitation when voltage raise above rated voltage(12V,24V,48V,96V) in order to remain 1800W output. On the other hand, when voltage is below rated voltage(12V,24V,48V,96V), the maximum current limitation will set at Max input current. 5. The efficiency is measured at 75% load. 6. The ambient temperature derating of 5℃/1000m with fan models for operating altitude higher than 2000m(6500ft). 7. CANBus model only. 8. During withstands voltage and isolation resistance testing, the screw "A" shall be temporarily removed, and shall be installed back after the testing. ※ Product Liability Disclaimer : For detailed information, please refer to https://www.meanwell.com/serviceDisclaimer.aspx				

2.4 Derating curve



2.5 Mechanical specification



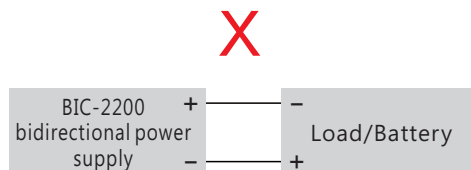
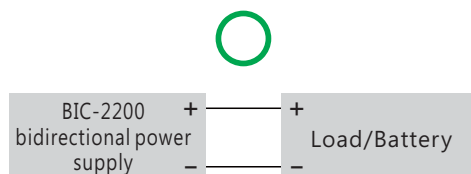
3.Installation & Wiring

3.1 Precautions

- Please make sure the system chassis has sufficient strength to carry the unit.
- In order to ensure the lifespan of the unit, you should refrain from operating the unit in environment of high dust or moisture.
- The bidirectional power supply is designed with built-in DC fans, please make sure the ventilation is not blocked. There should be no barriers within 15cm of the ventilating

3.2 Installation Procedures

- ① Choose the right and suitable cable size for connection between the BIC-2200 and the loads or batteries. Please refer to 3.3 DC cable size selection.
- ② Connect the DC positive polarity of the supply to the positive of the loads/batteries and connect the DC negative polarity of the supply to the negative of the loads/batteries. Make sure there is no reverse polarity or short-circuit on the connection.



- ③ Connect the supply to the AC grid, FG to the earth, AC/N to the neutral and AC/L to the live.
NOTE: The bidirectional power supply is single-phase input/output. Please pay attention to the wiring when connecting the supply to a three-phase system.

3.3 DC Cable Size Selection

Wire connections should be as short as possible and less than 1 meter is highly recommended. Make sure that suitable wires are chosen based on safety requirement and rating of current. Small cross section will result in lower efficiency, less output power and the wires may also become overheated and cause danger. For selection, please refer to table 3-1.

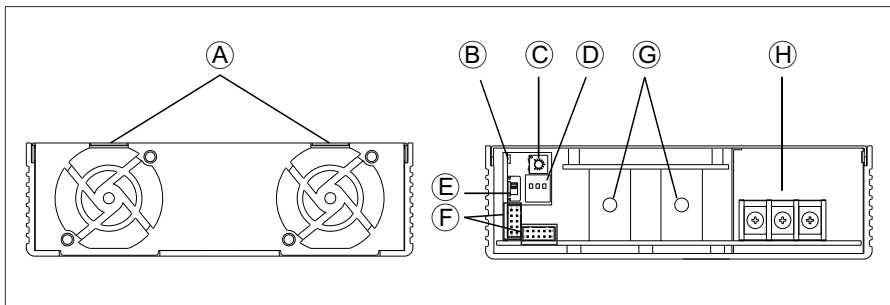
AWG	Cross-section Are(mm ²)	DC current (A)
8	6	32A ~ 40A
6	10	40A ~ 63A
4	16	63A ~ 80A
2	25	80A ~ 100A
1	35	100A ~ 125A
---	30	139A
---	50	190A
---	60	217A
---	80	257A

Table 3-1 Wire recommendations

4. User Interface

4.1 Panel Description

- Ⓐ **Ventilation holes for fans:**
The supply requires suitable ventilation to work properly. Please make sure there is sufficient ventilation and the lifespan of the supply can be preserved.
- Ⓑ **LED indicator:**
Indicate the status of supply and the load condition.
- Ⓒ **SVR:**
For DC voltage setting.
- Ⓓ **DIP switch:**
For device addressing when using the communication interface.
- Ⓔ **SW50:**
Used to stabilize parallel signals when multi-supplies in parallel connection.
- Ⓕ **Function pins:**
They are used for control and monitoring functions. Please refer to 4.3 and 4.4.
- Ⓖ **DC terminals**
- Ⓗ **AC terminals**

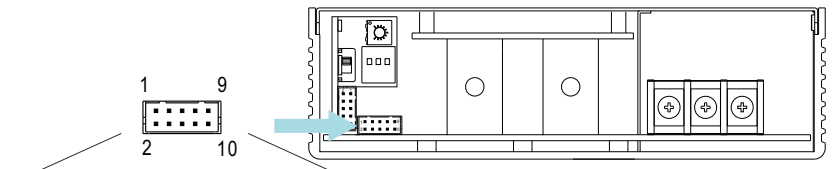


4.2 LED Indicator

The LED indicator is controlled by the microcontroller or the MCU. The MCU will change color of the indicator according to its operation status. The indicator lights in constant green when the supply is in operating mode; The indicator's flashing in green when the supply is in recycle mode; The indicator turns red when the supply is in abnormal conditions or protection mode.

LED Indicator	Status
● Green	Operating (AC to DC, work as an ordinary power supply or charger)
● Green (Flashing)	Recycle (DC to AC, work as a grid tie inverter)
● Red	Abnormal (OTP, OLP, fan-lock, etc...)

4.3 Pin Assignment of CN46



1	+12V-AUX	+5V-AUX	Remote ON-OFF	DC-OK	T-ALARM	9
2	GND-AUX	GND-AUX	C/D Control	Fault	NC	10

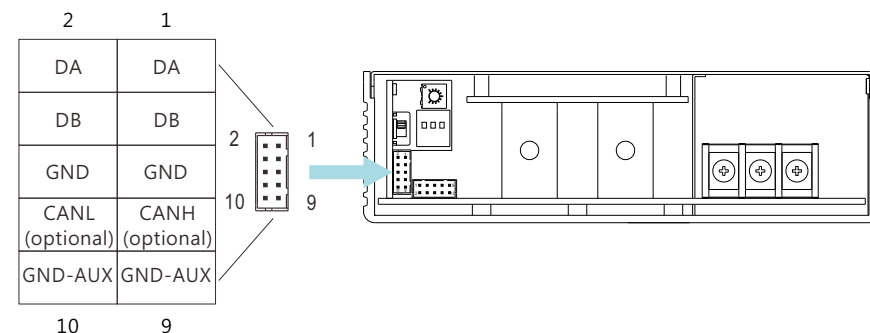
Pin No.	Function	Description
1	+12V-AUX	Auxiliary voltage output, 11.4~12.6V, referenced to GND-AUX (pin 2,4). The maximum output current is 0.5A. This output is not controlled by the Remote ON/OFF control.
2,4	GND-AUX	Auxiliary voltage output GND. The signal return is isolated from the output terminals (+V & -V).
3	+5V-AUX	Auxiliary voltage output, 4.5~5.5V, referenced to GND-AUX (pin 2,4) only for Remote ON/OFF used. This output is not controlled by the Remote ON/OFF control.

Pin No.	Function	Description
5	Remote ON-OFF	The unit can turn the output ON/OFF by electrical signal or dry contact between Remote ON/OFF and +5V-AUX(pin 3). (Note.1)
6	C/D Control (Note.2)	High (4.5 ~ 5.5V) : Battery Charging mode Low (-0.5 ~ 0.5V) : Battery Discharging mode (Note.1)
7	DC-OK	High (4.5 ~ 5.5V) : When the $V_{out} \leq 80\% \pm 5\%$. Low (-0.5 ~ 0.5V) : When $V_{out} \geq 80\% \pm 5\%$. The maximum sourcing current is 4mA and only for output.
8	Fault	High (4.5 ~ 5.5V) : When the $V_{ac} \leq 165V_{rms}$, OLP, SCP, OTP, OVP, AC Fail, fan lock, islanding protection. Low (-0.5 ~ 0.5V) : When $V_{ac} \geq 175V_{rms}$ and when power supply work normally. The maximum sourcing current is 4mA and only for output. (Note.1)
9	T-ALARM	High (4.5 ~ 5.5V) : When the internal temperature exceeds the limit of temperature alarm, or when any of the fans fails. Low (-0.5 ~ 0.5V) : When the internal temperature is normal, and when fans work normally. The maximum sourcing current is 4mA and only for output. (Note.1)
10	NC	-----

Note 1 : Isolated signal, referenced to GND-AUX.

Note 2 : CANBus model only.

4.4 Pin Assignment of CN47



Pin No.	Function	Description
1,2	DA	Differential digital signal for parallel control. (Note.1)
3,4	DB	
5,6	GND	Negative output voltage signal. Certain function reference. It can not be connected directly to the load.
7	CANH (CANBus model)	For CANBus model: Data line used in CANBus interface. (Note.2)
8	CANL (CANBus model)	For CANBus model: Data line used in CANBus interface. (Note.2)
9,10	GND-AUX	Auxiliary voltage output GND. The signal return is isolated from the output terminals (+V & -V).

Note 1 : Non-isolated signal, referenced to GND.

Note 2 : Isolated signal, referenced to GND-AUX.

4.5 Function Description of SW50

Parallel connection of the BIC-2200 is by digital differential signals. Units in parallel compensate and stabilize their output through the digital parallel signals. SW50 is a termination resistor which is used to prevent signal reflections, then increasing communication quality. For the usage of SW50, please refer to 5.9 Current Sharing.

4.6 Function Description of DIP Switch

Each unit should have their unique and own device address to communicate over CANBus. Please be aware that: This DIP switch only takes effect when the communication interface is used. It is not necessary to set this switch in general use. For details, please refer to 6.2 CANBus addressing.

5.Operation

BIC-2200 possesses AC to DC and DC to AC two way conversion functions. The conversion direction can be automatically detected and controlled by BIC-2200's internal firmware or manually switched by users according to different application requirements. Before entering detailed function explanation. Please refer to following definitions.

AC to DC (Energy absorbing and charging/ power supplying):

The BIC-2200 converts AC energy from the grid into DC energy for the battery or the loads. The operation principle is the same as an ordinary power supply or a charger.



DC to AC (Energy recycling and discharging):

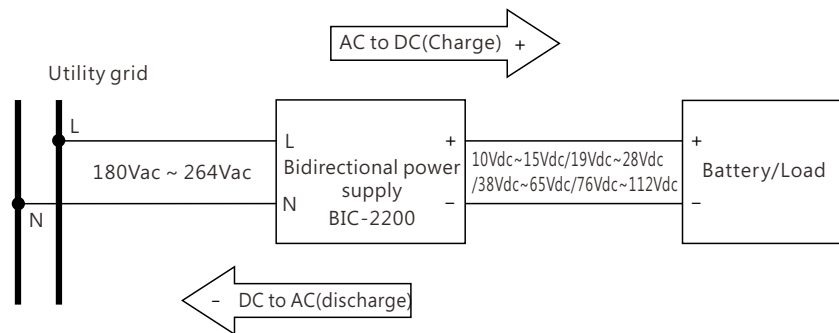
Opposite to the AC to DC conversion, the BIC-2200 converts DC energy from the battery or loads into AC energy, then feeding back to the grid. AC output synchronization range is 180Vac~264Vac/47Hz~63Hz, the bidirectional power supply can work normally as long as the AC grid is within the range.



5.1 Description of Bidirectional Operation

5.1.1 Overview

The output range of the BIC-2200 covers DC: 10V – 112V; AC: 180 – 264Vac / 47-63Hz, which can be used to applications with various voltage requirements, such as battery test equipment. To cope with different application occasions, there are two modes for selection, bi-direction auto-detect mode and programmable bi-direction battery mode.



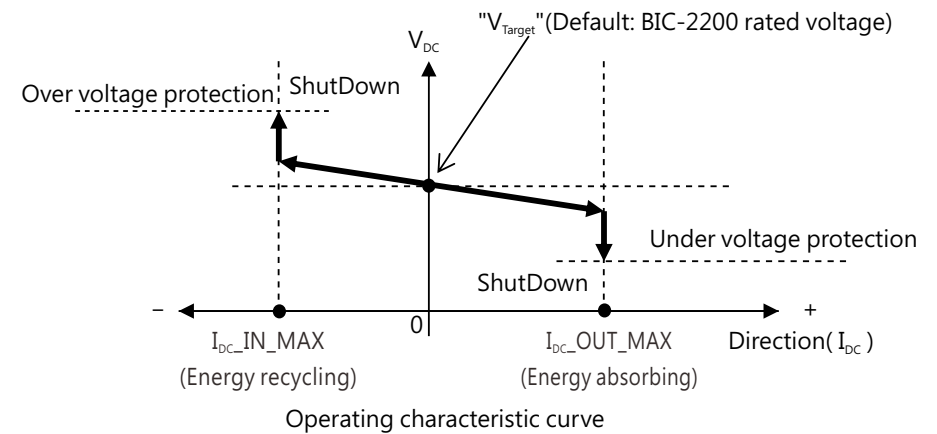
5.1.2 Bi-direction auto-detect mode

This is the default factory setting, AC to DC or DC to AC conversion is controlled by BIC-2200 automatically according to operation mechanism below.

- "Target voltage" is the DC voltage setting of the bidirectional supply, when the DC end voltage is different from the "target voltage", the internal firmware will switch between two conversion functions of AC to DC or DC to AC. "Target voltage" is adjustable by the SVR.
- When the "target voltage" is higher than the battery voltage or application equipment voltage, the BIC-2200 operates in AC to DC conversion.
- When the "target voltage" is lower than the battery voltage or application equipment voltage, the BIC-2200 operates in DC to AC conversion.

NOTE: During this mode, AC to DC or DC to AC conversion is judged by the internal firmware. Active control signal (e.g. C/D control) will not take effect in this mode.

Condition	Conversion
$V_{Target} > V_{DC}$	AC to DC
$V_{Target} < V_{DC}$	DC to AC



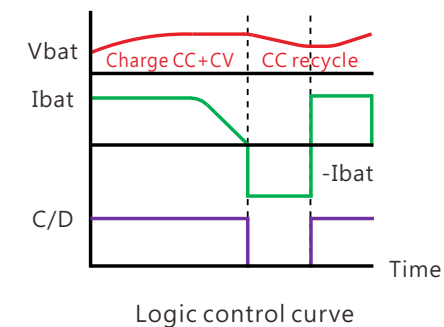
5.1.3 Bi-direction battery mode

This option only work with CANBus model, and with it's communication interface. To activate the mode, please follow below:

1. Set command SYSTEM_CONFIG(0x00C2) at 0x0003 → Activate CANBus communication mode.
2. Set command BIDIRECTIONAL_CONFIG(0x0140) at 0x0001 → Set at bi-direction battery mode.
3. Repower on the supply to activate the battery mode

NOTE: For detailed CANBus information, please refer to 6.CANBus Protocol

After bi-direction battery mode is activated, users can switch the supply between AC to DC or DC to AC conversion by CANBus command (digital) or C/D control (analogy). Please refer to 5.1.3.1 CANBus command (digital) and 5.1.3.2 C/D control (analogy)



5.1.3.1 CANBus command (digital)

The users can set the supply in AC to DC (charging) or DC to AC (discharging) conversion directly through command DIRECTION_CTRL (0x0100). Command VOUT_SET(0x0020) and IOUT_SET(0x0030) are used to adjust values of charge voltage and charge current in AC to DC conversion. Command REVERSE_VOUT_SET(0x0120) REVERSE_IOUT_SET(0x0130) are used to adjust values of discharging voltage and discharging current in DC to AC conversion.

Command	Conversion
DIRECTION_CTRL = 00h	AC to DC(charging)
DIRECTION_CTRL = 01h	DC to AC(discharging)

NOTE: Please refer to 6.5 CANBus value range and tolerance for detailed information about adjustable ranges of VOUT_SET, IOUT_SET, REVERSE_VOUT_SET and REVERSE_IOUT_SET.

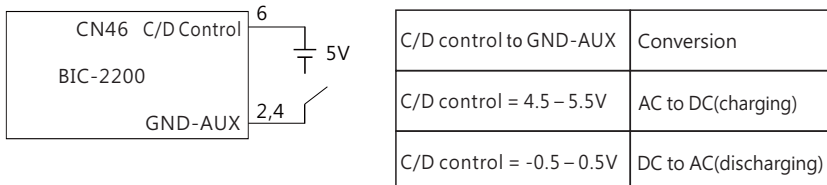
5.1.3.2 C/D Control (analogy)

The users also can control AC to DC (charging) or DC to AC (discharging) conversion via analogy signals. To activate the mode, please follow the steps below:

1.Set command BIDIRECTIONAL_CONFIG(0x0140) at "1" → Activate battery mode.

2.Set desired target voltage through

VOUT_SET(0x0020)/REV_VOUT_SET(0x0120) and AC/DC and DC/AC current through IOUT_SET(0x0030)/REV_IOUT_SET(0x0130)
AC/DC parameters: VOUT_SET(0x0020)/ IOUT_SET(0x0030)
DC/AC parameters: REV_VOUT_SET(0x0120)/ REV_IOUT_SET (0x0130)

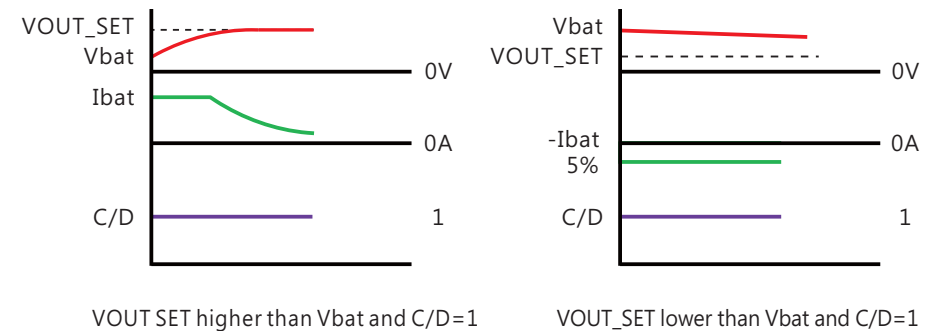


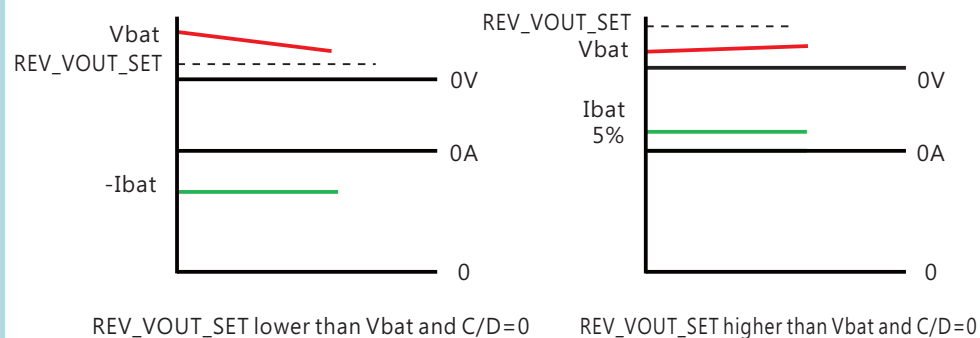
NOTE: Please make sure CAN_CTRL(Bit 0) of SYSTEM_CONFIG(0x00C2) is set at "0" in order not to interfere in C/D control.

5.1.3.3 Notes on battery mode

In bi-direction battery mode, although users can determine direction of the conversions on their demand, however if the setting voltage does not match the actual DC end voltage, AC to DC (charging) or DC to AC (discharging) conversion may not work as expected. Here are examples that will cause conversion errors.

1. During AC to DC conversion (C/D control = High or DIRECTION_CTRL = 00h), if battery voltage is higher than the value of command VOUT_SET (charge voltage), the BIC-2200 will perform DC to AC conversion instead, but limiting discharge current at 5% of rated current. If you want to ensure AC to DC conversion working properly, please make sure value of command VOUT_SET is higher than the battery voltage.
2. During DC to AC conversion (C/D control =Low or DIRECTION_CTRL = 01h), if battery voltage is lower than the value of command VOUT_SET_REV, the BIC-2200 will perform AC to DC conversion instead, but then limiting charge current at 5% of rated current. To ensure DC to AC conversion working properly, please make sure value of command VOUT_SET_REV is lower than the battery voltage.





5.2 Inrush Current Limiting

- Built-in AC inrush current limiting circuit
- Since the inrush current limiting circuit mainly consists of a NTC thermistor and a relay, inrush current will be much higher than the specified value if the thermistor in AC side is not allowed sufficient time to cool down. After turning off the supply, a 10 second cool down period is recommended before turning on again.

5.3 Power Factor Correction (PFC)

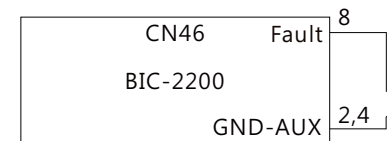
- Built-in active power factor correction (PFC) function, power factor (PF) will be 0.95 or better at full load condition in AC to DC or DC to AC conversion. PF will be less than 0.95 if it is not at full load condition during AC to DC or DC to AC conversion.

5.4 Fan Speed control

- Built-in fan speed control circuit, fan speed changes automatically depending on internal temperature.

5.5 Fault Signal

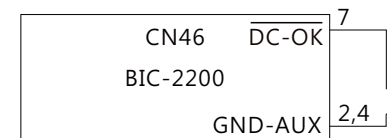
- Fault signal is used to inform application equipment that whether it is energy recyclable. When it is OLP, SCP or OTP, BIC-2200 will send a high level of fault signal 100ms in advance to notify the application before shutting down the supply. A fault signal will send out at the same time of shutting down operation in the reset of protection (e.g. AC_fail).
- Maximum output current 4mA.



CN46 Fault to GND-AUX	Condition
-0.5~0.5V	Normal working
4.5~5.5V	Not energy recyclable

5.6 (DC-OK) Signal

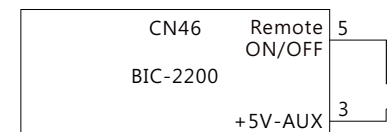
- Built-in DC output voltage detection circuit.
- Maximum output current 4mA.



CN46 DC-OK to GND-	Condition
-0.5~0.5V	DC OK
4.5~5.5V	Abnormal in DC

5.7 Remote Control

- Built-in remote ON/OFF control circuit, which is used to turn on/off the supply.
- Please be aware that "remote ON/OFF and "+5V-AUX" on CN46 should be linked together to allow the unit to operate normally; if kept open, there will be no output.
- Maximum input voltage 5.5V.



CN46 Remote ON/OFF to +5V-AUX	Condition
-0.5~0.5V	ON
4.5~5.5V	OFF

5.8 Auxiliary Output

- Built-in 12V/0.5A auxiliary output



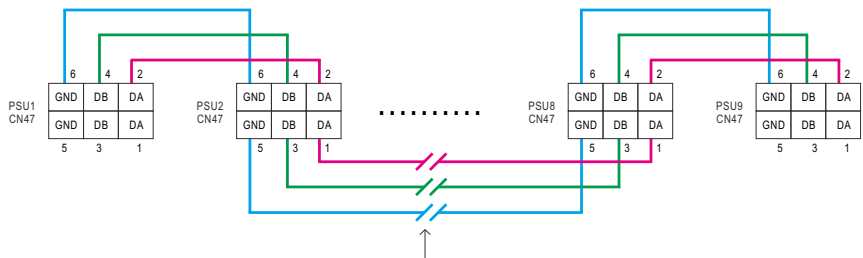
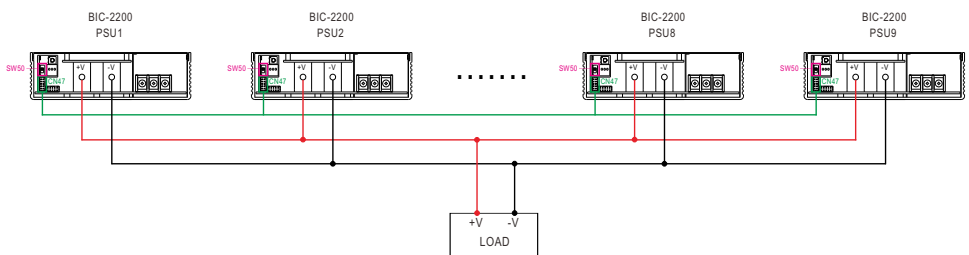
5.9 Parallel Operation

BIC-2200 has the built-in active current sharing function and can be connected in parallel, up to 9 units, to provide higher output power as exhibited below:

- The power supplies should be paralleled using short and large diameter wiring and then connected to the load.
- In parallel connection, power supply with the highest output voltage will be the master unit and its Vout will be the DC bus voltage.
- The total output current must not exceed the value determined by the following equation:
Maximum output current at parallel operation=(Rated current per unit) x (Number of unit) x 0.95
- When the total output current is less than 5% of the total rated current, or say (5% of Rated current per unit) x (Number of unit) the current shared among units may not be balanced.
- CN47/SW50 Function pin connection

Parallel	PSU1		PSU2		PSU3		PSU4		PSU5		PSU6		PSU7		PSU8		PSU9	
	CN47	SW50	CN47	SW50	CN47	SW50	CN47	SW50	CN47	SW50	CN47	SW50	CN47	SW50	CN47	SW50	CN47	SW50
1 unit	X	ON	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—
2 unit	V	ON	V	ON	—	—	—	—	—	—	—	—	—	—	—	—	—	—
3 unit	V	ON	V	OFF	V	ON	—	—	—	—	—	—	—	—	—	—	—	—
4 unit	V	ON	V	OFF	V	OFF	V	ON	—	—	—	—	—	—	—	—	—	—
5 unit	V	ON	V	OFF	V	OFF	V	OFF	V	ON	—	—	—	—	—	—	—	—
6 unit	V	ON	V	OFF	V	OFF	V	OFF	V	OFF	V	ON	—	—	—	—	—	—
7 unit	V	ON	V	OFF	V	OFF	V	OFF	V	OFF	V	OFF	V	ON	—	—	—	—
8 unit	V	ON	V	OFF	V	OFF	V	OFF	V	OFF	V	OFF	V	OFF	V	ON	—	—
9 unit	V	ON	V	OFF	V	OFF	V	OFF	V	OFF	V	OFF	V	OFF	V	OFF	V	ON

(V : CN47 connected ; X : CN47 not connected)

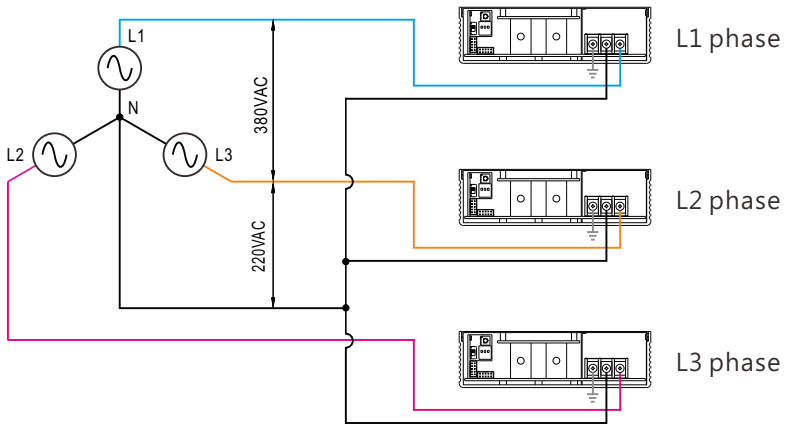


If the lines of CN47 are too long, they should be twisted in pairs to avoid the noise.

© DA、DB Connected mutually in parallel

5.9.1 Parallel Operation with 3-phase 4-wire System

When operating BIC-2200 units in parallel, their AC side can be connected to either a single-phase or three-phase, four-wire AC system. To ensure balanced current distribution in the AC system, it is generally recommended to evenly distribute the BIC-2200 units across the phases. For example, when using nine BIC-2200 units in parallel, three units can be connected with AC/L to L1 and AC/N to N, another three units with AC/L to L2 and AC/N to N, and the remaining three with AC/L to L3 and AC/N to N, as illustrated in the diagram below.



5.10 Restore Factory Default Setting

Users could set the device into factory default by following steps (command 0x0000, 0x0020, 0x0120, 0x0030, 0x0130, 0x0140, 0x00C2):

- ① Set all DIP switch positions (device address) to ON.
- ② Power on in REMOTE OFF mode (no output at this step).
- ③ After power on, in 15 seconds, switch all DIP switch from ON to OFF and then switch ALL back to ON position.
- ④ Green LED will blink 3 times if set successfully.
- ⑤ If the EEPROM storage function was DISABLE (high byte bit 2 set to "logic 1" in SYSTEM_CONFIG(0x00C2)), please perform step ① - ④ again to fully restore the parameters back to factory settings.

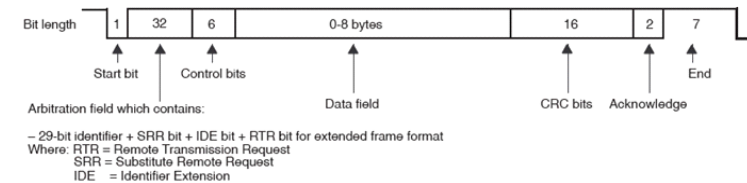


6.CANBus Protocol

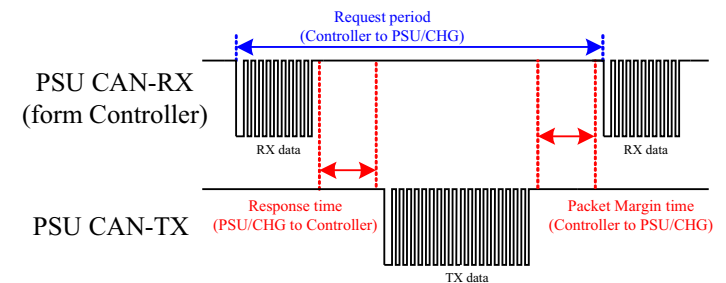
CANBus communication interface provides control and monitoring functions. It is helpful when users intent to modify the parameters remotely. Users can read and write the parameters through the bus, which includes bi-directional battery mode switch, ON/OFF, charge voltage/ current, discharge voltage/ current, temperature, etc.

6.1 CANBus Specification

- Physical layer specification
This protocol follows CAN ISO-11898 with Baud rate of 250Kbps.
- Data Frame
This protocol utilizes Extended CAN 29-bit identifier frame format or CAN 2.0B.



- Communication Timing
Min. request period (Controller to BIC-2200): 20mSec
Max. response time (BIC-2200 to Controller): 5mSec
Min. packet margin time (Controller to BIC-2200): 5mSec



- Data Field Format

Controller to BIC

Write: Please refer to section 6.4.1

Data filed bytes

0	1	2	3
COMD. low byte	COMD. high byte	Data low byte	Data high byte

Read: Please refer to section 6.4.2

Data filed bytes

0	1
COMD. low byte	COMD. high byte

BIC to Controller

Response: Please refer to section 6.4.2

Data filed bytes

0	1	2	7
COMD. low byte	COMD. high byte	Data low 1		Data high 6

NOTE: BIC will not send data back when write parameters, such as VOUT_SET

6.2 CANBus Addressing

- Each BIC-2200 unit should have their unique and own device address to communicate over the CANBus. PIN 1 - PIN 3 of the DIP switches allow users to designate an address for their supply units (with maximum of 8 addresses).

Message ID definition:

Description	Message ID
BIC-2200 to controller Message ID	0x000C02XX
Controller to BIC-2200 Message ID	0x000C03XX
Controller broadcasts to BIC-2200 Message ID	0x000C03FF

- XX indicates the device number of the BIC-2200, which can be assigned by the DIP switches, ranging from 0x00 ~ 0x07.



Device No.	DIP switch position		
	1	2	3
0	ON	ON	ON
1	OFF	ON	ON
2	ON	OFF	ON
3	OFF	OFF	ON
4	ON	ON	OFF
5	OFF	ON	OFF
6	ON	OFF	OFF
7	OFF	OFF	OFF

6.2.1 Extension of Device Addresses

Due to the limitation of the three DIP switches, the device can only support a maximum of 2^3 , or 8 unique device numbers/addresses. To enable communication among nine BIC-2200 units, the device address range can be extended to 0 - 63 by using the following setup. Although the maximum number of devices online remains nine, this extension offers greater flexibility for different applications.

Definition of the Extended Device Addresses:

Device No.	Basic addressing			Extended addressing		
	A0	A1	A2	A3	A4	A5
	DIP switch position			DIP switch position		
	1	2	3	1	2	3
0	ON	ON	ON	ON	ON	ON
1	OFF	ON	ON	ON	ON	ON
2	ON	OFF	ON	ON	ON	ON
⋮						
61	OFF	ON	OFF	OFF	OFF	OFF
62	ON	OFF	OFF	OFF	OFF	OFF
63	OFF	OFF	OFF	OFF	OFF	OFF

※ Default values of A3, A4, A5 = ON, ON, ON

◎ Please follow the steps below to configure the device with extended addressing settings:

- ① Turn off AC power and set all DIP switches to OFF.
- ② Apply AC power with the unit in REMOTE OFF mode. There should be no output at this step.
- ③ Within 15 seconds after AC power is applied, toggle the position 3 of the DIP switches from OFF to ON, then back to OFF.



- ④ The LED will blink in green five times and then off, indicating that the DIP switches are ready to configure A3, A4, and A5.
- ⑤ Within 10 seconds after the blinking, begin setting A3, A4, and A5. After setting, leave the DIP switches in place for the remaining time. The LED will blink green five times and turn off, indicating that the configuration is saved.
- ⑥ After cycling the AC power, set A0, A1 and A2 to complete the rest of the address settings.

Note:

1. The maximum verified number of communication units on the bus is 9. If additional units are required for the system, please contact MEAN WELL.
2. Since the extended addresses (A3 - A5) cannot be visually confirmed on the device, it is recommended to label the unit after configuration to avoid reconfiguration later.

Message ID Extension Example: setting device ID to 62

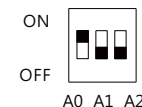
1. Turn off AC power and set all DIP switches to OFF.
2. Apply AC power with the unit in REMOTE OFF mode. There should be no output at this step.
3. Within 15 seconds after AC power is applied, toggle DIP switch position 3 from OFF to ON, then back to OFF.



4. The LED will blink green five times and then turn off, indicating that the DIP switches are ready to configure A3, A4, and A5.
5. Within 10 seconds of the blinking, set A3, A4, and A5 to OFF, OFF, OFF. After setting, leave the DIP switches in place for the remaining time. The LED will blink green five times and turn off, indicating that the configuration has been saved.



6. After cycling the AC power, set A0, A1, and A2 to ON, OFF, OFF to complete the address settings.



6.3 CANBus command list

Command Code	Command Name	Transaction Type	# of data Bytes	Description
0x0000	OPERATION	R/W	1	01:ON/00:OFF
0x0020	VOUT_SET*	R/W	2	Charge voltage setting (Factor = 0.01)
0x0030	IOUT_SET*	R/W	2	Charge current setting (Factor = 0.01)
0x0040	FAULT_STATUS	R	2	Summary status reporting
0x0050	READ_VIN	R	2	AC voltage reading value (Factor = 0.1)
0x0060	READ_VOUT	R	2	DC voltage reading value (Factor = 0.01)
0x0061	READ_IOUT	R	2	DC current reading value (Factor = 0.01)
0x0062	READ_TEMPERATURE_1	R	2	Internal ambient temperature (Factor = 0.1)
0x0070	READ_FAN_SPEED_1	R	2	Fan speed 1 reading value (Factor = 1)
0x0071	READ_FAN_SPEED_2	R	2	Fan speed 2 reading value (Factor = 1)
0x0080	MFR_ID_B0B5	R	6	Manufacturer's name
0x0081	MFR_ID_B6B11	R	6	Manufacturer's name
0x0082	MFR_MODEL_B0B5	R	6	Manufacturer's model name
0x0083	MFR_MODEL_B6B11	R	6	Manufacturer's model name
0x0084	MFR_REVISION_B0B5	R	6	Firmware revision
0x0085	MFR_LOCATION_B0B2	R/W	3	Manufacturer's factory location
0x0086	MFR_DATE_B0B5	R/W	6	Manufacturer's date
0x0087	MFR_SERIAL_B0B5	R/W	6	Product serial number
0x0088	MFR_SERIAL_B6B11	R/W	6	Product serial number

Command Code	Command Name	Transaction Type	# of data Bytes	Description
0x00C0	SCALING_FACTOR	R	2	Scaling ratio
0x00C1	SYSTEM_STATUS	R	2	System status
0x00C2	SYSTEM_CONFIG	R/W	2	System configuration
0x0100	DIRECTION_CTRL	R/W	1	A/D or D/A conversion control 00: A/D 01: D/A
0x0120	REVERSE_VOUT_SET*	R/W	2	Discharge voltage setting (Factor = 0.01)
0x0130	REVERSE_IOUT_SET*	R/W	2	Discharge current setting (Factor = 0.01)
0x0140	BIDIRECTIONAL_CONFIG	R/W	2	Bidirectional mode configuration

NOTE: Setting commands with * at the end support the EEP_OFF and EEP_CONFIG functions. For detailed information on how to enable them, please refer to SYSTEM_CONFIG (0x00C2).

Data conversion:

The calculation for setting and reading values is defined as:

Actual Value = Communication Read Value × Factor Value,

where the factor value is used for both writing and reading during communication for data conversion. Each command may have a different factor value, which can be found in the command list or retrieved from the **SCALING_FACTOR (0x00C0)** command.

For Example:

If the communication read value for the **READ_VOUT** command is 0x0960 (hexadecimal), and the factor value for the command is 0.01:

Actual Value = 0x0960 (hex) → 2400 (decimal) × 0.01 = 24V.

FAULT_STATUS(0x0040):

High byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition	---	---	---	---	---	---	---	HV_OVP
Low byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition	HI_TEMP	OP_OFF	AC_FAIL	SHORT	OLP	OVP	OTP	FAN_FAIL

Low byte :

Bit 0 FAN_FAIL : Fan locked flag

0 = Fan working normally

1 = Fan locked

Bit 1 OTP : Over temperature protection

0 = Internal temperature normal

1 = Internal temperature abnormal

Bit 2 OVP : DC over voltage protection

0 = DC voltage normal

1 = DC over voltage protected

Bit 3 OLP : DC over current protection

0 = DC current normal

1 = DC over current protected

Bit 4 SHORT : Short circuit protection

0 = Shorted circuit do not exist

1 = Shorted circuit protected

Bit 5 AC_FAIL : AC abnormal flag

0 = AC range normal

1 = AC range abnormal

Bit6 OP_OFF : DC status

0 = DC turned on

1 = DC turned off

Bit7 HI_TEMP : Internal high temperature alarm

0 = Internal temperature normal

1 = Internal temperature high

High byte :

Bit 0 HV_OVP : HV over voltage protection

0 = HV voltage normal

1 = HV over voltage protected

MFR_ID_B0B5(0x0080) is the first 6 codes of the manufacturer's name (ASCII); MFR_ID_B6B11(0x0081) is the last 6 codes of the manufacturer's name (ASCII)

EX: manufacturer's name is MEANWELL → MFR_ID_B0B5 is MEANWE ;

MFR_ID_B6B11 is LL

MFR_ID_B0B5					
Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x4D	0x45	0x41	0x4E	0x57	0x45

MFR_ID_B6B11					
Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x4C	0x4C	0x20	0x20	0x20	0x20

MFR_MODEL_B0B5(0x0082) is the first 6 codes of the manufacturer's model name(ASCII); MFR_MODEL_B6B11(0x0083) is the last 6 codes of the manufacturer's model name (ASCII)

EX: Model name is BIC-2200-24 → MFR_MODEL_B0B5 is BIC-22 ;

MFR_MODEL_B6B11 is 00-24

MFR_MODEL_B0B5					
Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x42	0x49	0x43	0x2D	0x32	0x32

MFR_MODEL_B6B11					
Byte 6	Byte 7	Byte 8	Byte 9	Byte 10	Byte 11
0x30	0x30	0x2D	0x32	0x34	0x20

MFR_REVISION_B0B5(0x0084) is the firmware revision (hexadecimal). A range of 0x00(R00.0)~0xFE (R25.4) represents the firmware version of an MCU; 0xFF represents no MCU existed

EX: The supply has two MCUs, the firmware version of the MCU number 1 is version R25.4 (0xFE), the MCU number 2 is version R10.5 (0x69)

Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0xFE	0x69	0xFF	0xFF	0xFF	0xFF

MFR_DATE_B0B5(0x0086) is manufacture date (ASCII)

EX: MFR_DATE_B0B5 is 180101, meaning 2018/01/01

Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x31	0x38	0x30	0x31	0x30	0x31

MFR_SERIAL_B0B5(0x0087) and MFR_SERIAL_B6B11(0x0088) are defined as manufacture date and manufacture serial number (ASCII)
 EX: The first unit manufactured on 2018/01/01 → MFR_SERIAL_B0B5: 180101 ; MFR_SERIAL_B6B11: 000001

MFR_ID_B0B5						MFR_ID_B6B11					
Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7	Byte 8	Byte 9	Byte 10	Byte 11
0x31	0x38	0x30	0x31	0x30	0x31	0x30	0x30	0x30	0x30	0x30	0x31

SCALING_FACTOR(0x00C0):

Byte 3~5	Bit 7~Bit 0							
Definition	---							
Byte 2	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition	--				TEMPERATURE_1 Factor			
Byte 1	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition	FAN_SPEED Factor				VIN Factor			
Byte 0	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition	IOUT Factor				VOUT Factor			

byte 0 :

Bit 0 : 3 **VOUT Factor : The factor value for DC voltage-related commands, such as VOUT_SET**

0x0=DC voltage relevant commands not supported
 0x4=0.001
 0x5=0.01
 0x6=0.1
 0x7=1.0
 0x8=10
 0x9=100

Bit 4 : 7 0x9=100

IOUT Factor : The factor value for DC current-related commands, such as READ_IOUT

0x0=DC current relevant commands not supported
 0x4=0.001
 0x5=0.01
 0x6=0.1
 0x7=1.0
 0x8=10
 0x9=100

byte 1 :

Bit 0 : 3 **VIN Factor : The factor value of READ_VIN**

0x0=AC voltage relevant commands not supported
 0x4=0.001
 0x5=0.01
 0x6=0.1
 0x7=1.0
 0x8=10
 0x9=100

Bit 4 : 7 **FAN_SPEED Factor : The factor value of READ_FAN_SPEED_1/2**

0x0=Fan speed relevant commands not supported
 0x4=0.001
 0x5=0.01
 0x6=0.1
 0x7=1.0
 0x8=10
 0x9=100

byte 2 :

Bit 0 : 3 **TEMPERATURE_1 Factor : The factor value of READ_TEMPERATURE_1**

0x0=Internal ambient temperature relevant commands not supported
 0x4=0.001
 0x5=0.01
 0x6=0.1
 0x7=1.0
 0x8=10
 0x9=100

SYSTEM_STATUS(0x00C1):

High byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition	---	---	---	---	---	---	---	---
Low byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition	---	EEPER	INITIAL_STATE	ADL_ON	---	PFC_OK	DC_OK	M/S

Low byte :

Bit 0 M/S : parallel mode status

- 0 = Current device is Slave
- 1 = Current device is Master

Bit 1 DC_OK : Secondary DD output voltage status

- 0 = Secondary DD output voltage status TOO LOW
- 1 = Secondary DD output voltage status NORMAL

Bit 2 PFC_OK : Primary PFC status

- 0 = Primary PFC OFF or abnormal
- 1 = Primary PFC ON normally

Bit 4 ADL_ON : Operation status of the active dummy loads

- 0 = Active dummy load off/function not supported
- 1 = Active dummy load on

Bit 5 INITIAL_STATE: Device initialized status

- 0 = In initialization status
- 1 = NOT in initialization status

Bit6 EEPER : EEPROM data access error

- 0 = EEPROM data access normal
- 1 = EEPROM data access error

※ When an EEPROM data access error occurs, the supply shuts down and then entering protection mode with the LED indicator off. It only can be recovered after the EEPROM error condition is resolved.

SYSTEM_CONFIG(0x00C2):

High byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition	---	---	---	---	---	EEP_OFF	EEP_CONFIG	
Low byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition	---	---	---	---	---	OPERATION_INIT	CAN_CTRL	

Low byte :

Bit 0 CAN_CTRL : CANBus communication control status

- 0 = The output voltage/current defined by control over SVR
- 1 = The output voltage, current, ON/OFF control defined by control over CANBus (VOUT_SET, IOUT_SET, OPERATION)

Bit1 : 2 OPERATION_INIT : Pre-set value of power on operation command

- 0b00 = Power OFF, pre-set 0x00(OFF)
- 0b01 = Power ON, pre-set 0x01(ON)
- 0b10 = Pre-set is previous set value
- 0b11 = not used, reserved

High Byte

Bit 0 : 1 EEP_CONFIG : EEPROM Configuration

- 00: Immediate. Changes to parameters are written to EEPROM immediately (factory default)
- 01: 1 minute delay. Write changes to EEPROM if all parameters remain unchanged for 1 minute
- 10: 10 minute delay. Write changes to EEPROM if all parameters remain unchanged for 10 minutes
- 11: Reserved

Bit 2 EEP_OFF : EEPROM storage function ON/OFF

- 0: Enable. Parameters to be saved into EEPROM (factory default)
- 1: Disable. Parameters NOT to be saved into EEPROM

BIDIR_CONFIG(0x0140):

High byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition	---	---	---	---	---	---	---	---
Low byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition	---	---	---	---	---	---	---	MODE

Low byte :

Bit 0 MODE: Bidirectional mode configuration

- 0 = Bi-direction auto-detect mode. DIR_CTRL and C/D control (analogy) UN-controllable.
- 1 = Bi-direction battery mode. DIR_CTRL and C/D control (analogy) controllable

6.4 Communication Examples

The following provides examples of command sending and data reading for the CAN bus protocol.

6.4.1 Sending command

The master adjusts output voltage of the unit with address "00" to 30V.

CAN ID	DLC(data length)	Command code	Data
0x000C0300	0x4	0x2000	0xB80B

Command code: 0x0020(VOUT_SET) → 0x20(Lo) + 0x00(Hi)

Data: 30V → 3000 → 0x0BB8 → 0xB8(Lo) + 0x0B(Hi)

NOTE: Conversion factor for VOUT_SET is 0.01, so $\frac{30V}{0.01} = 3000$

6.4.2 Reading data or status

The master reads operation setting from the unit with address "01"

CAN ID	DLC(data length)	Command code
0x000C0301	0x2	0x0000

The unit with address "01" returns data below:

CAN ID	DLC(data length)	Command code	Data
0x000C0201	0x3	0x0000	0x01

Data: 0x01 ON, meaning that the unit with address "01" is operating.

6.4.3 Practical Operation of Communication Mode

The following steps will describe how to set the BIC-2200-48 to communication mode and adjust its voltage/current, with VOUT_SET: 60V, IOUT_SET: 20A and REVERSE_IOUT_SET: -20A.

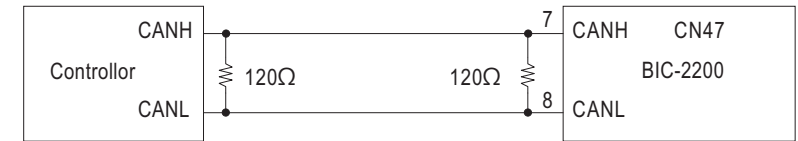
1. Set the ID of the BIC-2200 to "0", that is setting the DIP switch to ON/ON/ON positions.



2. Connect the CANH/CANL pins of the master to the corresponding CANH(PIN7) and CANL(PIN8) pins of the CN47 connector on the supply. It is recommended to establish a common ground for the communication system to increase its communication reliability by using GND-AUX (PIN9) of CN47.

◎ Set baud rate: 250kbps, type: extended

◎ Adding a 120Ω terminal resistor to both the controller and BIC-2200 ends can increase communication stability



3. Configure communication settings after power on in remote off mode. Enable communication mode and set power ON when AC connected.

CAN ID	DLC(data length)	Command code	Parameters
0x000C0300	0x04	0xC200	0x0300

Command code: 0x00C2(SYSTEM_CONFIG) → 0xC0 (Lo) + 0x00(Hi)
Parameters: 03(Lo) + 00(Hi) · Please refer to definition of SYSTEM_CONFIG for detailed information.

4. Set VOUT_SET to 60V.

CAN ID	DLC(data length)	Command code	Parameters
0x000C0300	0x04	0x2000	0x7017

Command code: 0x0020(VOUT_SET) → 0x20 (Lo) + 0x00(Hi)

Parameters: 60V → 6000 → 0x1770 → 0x70(Lo) + 0x17(Hi)

NOTE: Conversion factor for VOUT_SET is 0.01 · so $\frac{60V}{0.01} = 6000$

5. Set IOUT_SET to 20A.

CAN ID	DLC(data length)	Command code	Parameters
0x000C0300	0x04	0x3000	0xD007

Command code: 0x0030(IOUT_SET) → 0x30 (Lo) + 0x00(Hi)

Parameters: 20A → 2000 → 0x07D0 → 0xD0(Lo) + 0x07(Hi)

NOTE: Conversion factor for VOUT_SET is 0.01 · so $\frac{20A}{0.01} = 2000$

6. Set REVERSE_IOUT_SET to -20A.

CAN ID	DLC(data length)	Command code	Parameters
0x000C0300	0x04	0x3001	0xD007

Command code: 0x0130(REVERSE_IOUT_SET) → 0x30 (Lo) + 0x01(Hi)

Parameters: 20A → 2000 → 0x07D0 → 0xD0(Lo) + 0x07(Hi)

NOTE: Conversion factor for VOUT_SET is $0.01 \cdot \text{so } \frac{20\text{A}}{F0.01} = 2000$

7. Before connecting to the batteries or loads, it is recommended to review all of the settings and parameters using the appropriate commands. In the event that they do not meet your requirements, you may rewrite them as needed.

EX: Read IOUT_SET to check whether current level for AC to DC was set to a proper level.

Read IOUT_SET

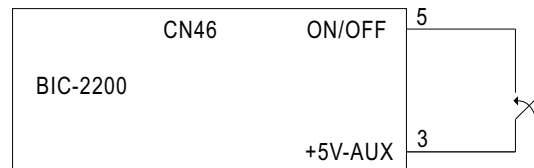
CAN ID	DLC(data length)	Command code
0x000C0300	0x02	0x3000

The unit returns data below

CAN ID	DLC(data length)	Command code	Parameters
0x000C0200	0x04	0x3000	0xD007

Parameters: 0xD0(Lo) + 0x07(Hi) → 0x07D0 → 6000 → $6000 \times 0.01(\text{F}) = 20\text{A}$

8. Finally, short circuit ON-OFF (PIN5) and +5-AUX (PIN3) pins of the CN46 connector on the supply to remote on it to charge the batteries or provide energy to the loads.



6.5 CANBus value range and tolerance

(1) Display parameters

CANBus Command		Model	Display value range	Tolerance
0x0050	READ_VIN	ALL	180~264V	±10V
0x0060	READ_VOUT	12V	0~15V	±0.12V
		24V	0~28V	±0.24V
		48V	0~56V	±0.48V
		96V	0~112V	±0.96V
0x0061	READ_IOUT	12V	-180~216A	±1.8A
		24V	-90~108A	±0.9A
		48V	-45~54A	±0.45A
		96V	-22.5~27A	±0.25A
0x0062	READ_TEMPERATURE_1	ALL	-40~110°C	±5°C
0x0070	READ_FAN_SPEED_1	ALL	0 ~ 25000RPM	±2000RPM
0x0071	READ_FAN_SPEED_2	ALL	0 ~ 25000RPM	±2000RPM

(2) Control parameters (Bi-direction auto-detect mode)

CANBus Command		Model	Adjustable range	Tolerance	Default
0x0000	OPERATION	ALL	00h(OFF)/01h(ON)	N/A	01h(ON)
0x0020	VOUT_SET	12V	10~15V	±0.12V	12V
		24V	19~28V	±0.24V	24V
		48V	38~65V	±0.48V	48V
		96V	76~112V	±0.96V	96V
0x0120	REVERSE_VOUT_SET	12V	10~15V	±0.12V	10V
		24V	19~28V	±0.24V	19V
		48V	38~65V	±0.48V	38V
		96V	76~112V	±0.96V	76V
0x0030	IOUT_SET	12V	+1.8~+198A	±1.8A	198A
		24V	+0.9~+99A	±0.9A	99A
		48V	+0.45~+49.5A	±0.45A	49.5A
		96V	+0.25~+24.75A	±0.25A	24.75A
0x0130	REVERSE_IOUT_SET	12V	-153~-1.8A	±1.8A	-153A
		24V	-76.5~-0.9A	±0.9A	-76.5A
		48V	-38.3~-0.45A	±0.45A	-38.3A
		96V	-19.1~-0.25A	±0.25A	-19.1A
0x0140	BIDIRECTIONAL_CONFIG	ALL	00h(CV)/01h(Battery)	N/A	00h(CV)
0x00C2	SYSTEM_CONFIG	ALL	N/A	N/A	02h
0x0000	OPERATION	ALL	00h(OFF)/01h(ON)	N/A	01h(ON)

(3)Control parameters (Bi-direction battery mode)

CANBus Command		Model	Adjustable range	Tolerance	Default
0x0100	DIRECTION_CTRL	ALL	00h(Charge)/ 01h(Discharge)	N/A	00h(Charge)
0x0020	VOUT_SET	12V	10~15V	±0.12V	12.6V
		24V	19~28V	±0.24V	25.2V
		48V	38~65V	±0.48V	50.4V
		96V	76~112V	±0.96V	100.8V
0x0120	REVERSE_VOUT_SET	12V	10~15V	±0.12V	10V
		24V	19~28V	±0.24V	19V
		48V	38~65V	±0.48V	38V
		96V	76~112V	±0.96V	76V
0x0030	IOUT_SET	12V	+1.8~+180A	±1.8A	160A
		24V	+0.9~+90A	±0.9A	80A
		48V	+0.45~+45A	±0.45A	40A
		96V	+0.25~+22.5A	±0.25A	20A
0x0130	REVERSE_IOUT_SET	12V	-153~-1.8A	±1.8A	-120A
		24V	-76.5~-0.9A	±0.9A	-64.3A
		48V	-38.3~-0.45A	±0.45A	-32.2A
		96V	-19.1A~-0.25A	±0.25A	-16.1A
0x0140	BIDIRECTIONAL_CONFIG	ALL	00h(AD)/01h(BAT.)	N/A	00h(AD)
0x00C2	SYSTEM_CONFIG	ALL	N/A	N/A	02h

NOTE:

- i. Owing to the limited write cycles of the EEPROM, it is advisable to consider using the SYSTEM_CONFIG (0x00C2) command to select an appropriate EEPROM writing logic, especially if communication settings are frequently altered.
- ii. Changing parameters to BIDIR_CONFIG(0x0140) command require a reboot to take effect.

7. Protections and Trouble Shooting

7.1 Protections

7.1.1 Anti-islanding Protections

BIC-2200 is designed to refer to IEC 62116(2008), the supply shuts off within 2 seconds when AC is cut or abnormal. Please be aware that it is necessary to install an AC circuit breaker that complies with grid-tie standard in your country before the supply.

7.1.2 Over Temperature Protection (OTP) and Alarm

Built-in thermal detection circuit, once the internal temperature exceeds a threshold value, the supply will shut down automatically (the fans will still be running to cool down the supply). Please switch off the supply, remove all possible causes and then leave the supply cooling down to a normal working temperature (approximate 10 minutes - 1 hour) before repower on again.

Maximum output current 4mA.

<div><div>CN46 T-ALARM</div><div>BIC-2200</div><div>GND-AUX</div></div>	9		CN46 T-ALARM to GND-AUX	Condition
			-0.5~0.5V	Normal Temp.
	2,4		4.5~5.5V	Abnormal temp.

7.1.3 AC Fail Protection

When AC voltage/frequency is abnormal, BIC-2200 will enter protection mode to prevent damaging itself or affect quality of the grid no matter which conversion it is, D/A or A/D. The supply will restore automatically when AC voltage/frequency back to normal.

7.1.4 Short Circuit Protection

When there is short circuit at AC/DC end of BIC-2200, the supply will enter protection mode and shut down. Repower on to restore after short-circuit condition is resolved.

7.1.5 Over Current Protection

In AC to DC conversion, when the load current exceeds $110\% \pm 5\%$ of the rated current, protection mode will be triggered. Repower on to restore after over-current condition is resolved.

7.1.6 DC Over Voltage Protection

When the DC end voltage is too high, the DC over-voltage protection circuit will be triggered. Repower on to restore after over-voltage condition is resolved.

7.2 Trouble Shooting

Failure State	Possible Cause	Suggested Solution
The supply is not working	Remote OFF	Make sure remote ON/OFF is connected to +5V
AC/DC or DC/AC conversion is incorrect	The setting voltage doesn't match actual DC end voltage	If it is bi-direction auto-detect mode, please refer to 5.1.2. If it is bi-direction battery mode, please refer to 5.1.3.3
LED shows abnormal indication	The ambient temperature too high	Re-start the supply after temperature dropped back
	DC load current too high	Re-start the supply after reducing DC load current
	AC voltage/frequency abnormal	Re-start the supply after AC voltage/frequency is within a normal range
	Battery or load voltage too high	Re-start the supply after DC end voltage is within a normal range

If you are unable to clarify the problem you are facing, please contact MEAN WELL or any of our distributors for repair service.

8. Warranty

This product provides five years warranty under normal usage. Do not replace parts or any form of modification to the product in order to keep the warranty effectively.

※ MEAN WELL possesses the right to adjust the content of this manual.

Please refer to the latest version of our manual on our website.

<https://www.meanwell.com>



9. Environmental declaration information

https://www.meanwell.com/Upload/PDF/RoHS_PFOS.pdf

https://www.meanwell.com/Upload/PDF/REACH_SVHC.pdf

https://www.meanwell.com/Upload/PDF/Declaration_RoHS-E.pdf

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